Designs on strongly regular graphs

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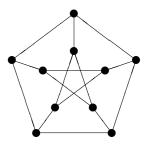
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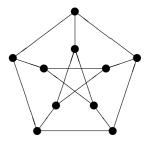
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- ▶ if two vertices are joined by an edge, then they have *p* common neighbours, for some constant *p*;
- if two vertices are not joined by an edge, then they have q common neighbours, for some constant q;
- the graph is neither complete nor null.

This is a famous strongly regular graph.

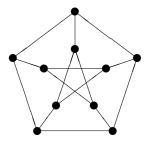


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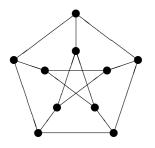
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- ▶ the adjacency matrix A has $A_{\alpha,\beta} = 1$ if $\{\alpha, \beta\}$ is an edge, and all other entries zero;
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In this case, the real vector space \mathbb{R}^{Ω} is the orthogonal direct sum of subspaces W_0 , W_1 and W_2 , each of which is (contained in) an eigenspace of A and an eigenspace of J, where W_0 is the one-dimensional subspace spanned by the all-1 vector \mathbf{u} .

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I will illustrate each of these conditions when applied to the same two combinatorial objects (aka networks).

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$$\operatorname{Cov}(Y_{\alpha},Y_{\beta}) = \left\{ \begin{array}{ll} \sigma^2 & \text{if } \alpha = \beta \\ \rho_1 \sigma^2 & \text{if } \alpha \neq \beta \text{ and } \{\alpha,\beta\} \text{ is an edge of } \Gamma \\ \rho_2 \sigma^2 & \text{otherwise.} \end{array} \right.$$

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The eigenspaces of Cov(Y) are W_0 , W_1 and W_2 . Call the corresponding eigenvalues γ_0 , γ_1 and γ_2 . We do not know the values of γ_0 , γ_1 and γ_2 in advance. When is the choice of best design not affected by the values of γ_0 , γ_1 and γ_2 ?

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Solution The subspace V_T of \mathbb{R}^Ω consisting of vectors which are constant on each treatment can be orthogonally decomposed as

$$W_0 \oplus (V_T \cap W_1) \oplus (V_T \cap W_2).$$

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Combinatorial Structure 1: Partition into Blocks

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An example of a balanced incomplete-block design

Here is a balanced incomplete-block design with b = 14, k = 4, t = 8 and $\lambda = 3$.

1	3	5	7	2	4	6	8
1	2	5	6	3	4	7	8
1	2	3	4	5	6	7	8
1	4	5	8	2	3	6	7
1	3	6	8	2	4	5	7
1	2	7	8	3	4	5	6
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Design and Analysis of Networked Experiments

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- (b) $V_T \leq W_0 \oplus W_1$.

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(c) $V_T \cap W_1$ and $V_T \cap W_2$ are both non-zero, and

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More generally, any subset of treatments may be merged into a single treatment. For example,



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1	1	1	ח	ח	ח	Λ	1	1	l	ח	ח	D
$\perp A$	$\mid A \mid$	A	В	B	В	1 <i>A</i> 1	1 <i>A</i> 1	A	l	l B	B	В
			_	_	~				l	_	_	~

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Such designs are used when management constraints make it impractical to apply the treatments to the individual plots.

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A1 | A2 | A3

B1 | B2 | B3

A1 | A2 | A3

B1 B2 B3

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These are called split-plot designs, and are widely used in practice.

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This structure is also useful in experiments where pairs of individuals are required to complete some task, with both individuals playing the same role.

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In situtations where the gender of the parent is irrelevant, it is efficient to use half-diallel experiments, in which the experimental units consist of all unordered crosses between m parental lines, excluding self-crosses.

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This happens in some experiments in human-computer interaction (which I was involved in at QMUL).

For example, the aim of the experiment might be to compare different methods for researchers to collaborate when they are unable to meet face-to-face, such as email, online meetings, old-fashioned letters, telephone calls with and without video.

Combinatorial Structure 2: more detail

Now the set Ω consists of all unordered pairs from the set $\{1, 2, ..., m\}$ of m distinct individuals, where $m \ge 4$.

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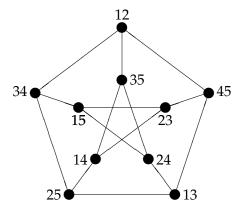
This is called the triangular graph T(m).

It is strongly regular, and its adjacency matrix A satisfies

$$A^2 = (2m - 8)I + (m - 6)A + 4J.$$

The Petersen graph again

This labelling of the vertices shows that it is the complement of the triangular graph T(5).



Bailey

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	1	2	3	4	5
2					
3					
4					
5					
6					

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	1	2	3	4	5
2					
3					
4					
5			*		
6					

$$* = {3,5}$$

When m=6 the set Ω has 15 elements, which can be shown as the cells of a 6×6 square lying below the main diagonal.

	1	2	3	4	5
2					
3	0	0			
4			0		
5	0	0	*	0	
6			0		0

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 \circ = vertices joined to vertex $\{3,5\}$

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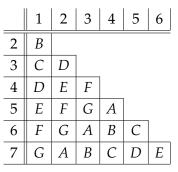
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Bailev

	1	2	3	4	5	6
2	В					
3	С	D				
4	D	Е	F			
5	Е	F	G	Α		
6	F	G	A	В	С	
7	G	A	В	C	D	Ε

	1	2	3	4	5	6
2	В					
3	С	D				
4	D	Е	F			
5	Е	F	G	Α		
6	F	G	A	В	С	
7	G	A	В	С	D	Ε

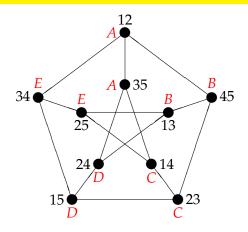
Treatment *A* occurs once with every individual except individual 1.



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For strongly regular graphs in general, such designs are called balanced colourings of strongly regular graphs.

This design on the Petersen graph



For each treatment, there is one edge that has that treatment on both vertices.

For each pair of distinct treatments, there is one edge that has them on its endpoints.

For i = 1, ..., m, let \mathbf{v}_i be the vector taking the value 1 on each pair that includes individual i and value 0 elsewhere. Let V_{ind} be the m-dimensional subspace of \mathbb{R}^{Ω} spanned by $\mathbf{v}_1, ..., \mathbf{v}_m$.

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Condition 2 We want the linear combination of the Y_{ω} (for $\omega \in \Omega$) which gives the best estimate of $\tau_C - \tau_D$ (correct on average, smallest variance) to be the same as the best estimator when $\gamma_0 = \gamma_1 = \gamma_2$. This is the difference between the averages for vertices with treatment C and those with treatment D.

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Design and Analysis of Networked Experiments

- (a) $V_T < W_0 \oplus W_2$.
- (b) $V_T < W_0 \oplus W_1$.

Bailey

(c) $V_T \cap W_1$ and $V_T \cap W_2$ are both non-zero, and $V_T = W_0 \oplus (V_T \cap W_1) \oplus (V_T \cap W_2)$.

 $VT = VV() \oplus (VT + VV1)$ Designs on strongly regular graphs

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Bailev

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(Start with a Latin square of the previous type; add an extra row at the bottom; move every diagonal element down to the bottom row; then put a dummy like ∞ on every diagonal cell.)

	1	2	3	4	5	6	7
2	С						
3	D	Е					
4	Е	F	G				
5	F	G	Α	В			
6	G	Α	В	С	D		
7	A	В	С	D	Е	F	
8	В	D	F	A	С	Е	G

	1	2	3	4	5	6	7
2	С						
3	D	Е					
4	Е	F	G				
5	F	G	Α	В			
6	G	Α	В	С	D		
7	Α	В	С	D	Е	F	
8	В	D	F	A	С	Ε	G

Each treatment occurs exactly once with each individual.

	1	2	3	4	5	6	7
2	С						
3	D	Е					
4	Е	F	G				
5	F	G	Α	В			
6	G	Α	В	С	D		
7	A	В	С	D	Е	F	
8	В	D	F	A	С	Ε	G

Each treatment occurs exactly once with each individual. Just as with complete-block designs, any subset of treatments may be merged into a single treatment.

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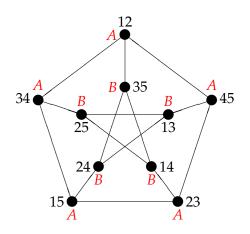
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When m = 9 this gives

	1	2	3	4	5	6	7	8	
2	1								
3	2	1							
4	3	2	1						
5	4	3	2	1					
6	4	4	3	2	1				
7	3	4	4	3	2	1			
8	2	3	4	4	3	2	1		
9	1	2	3	4	4	3	2	1	

Solution (a) for Condition 2 when m=5



Here *A* represents $\pm 1 \mod 5$ and *B* represents $\pm 2 \mod 5$.

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There is essentially only one solution.

There are precisely two treatments, say A and B. There is one special individual i. Treatment A is applied to all pairs containing i, and treatment B is applied to all other pairs.

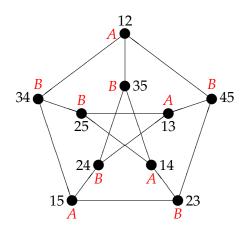
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	1	2	3	4	5	6	7	8	
2	A								
3	A	В							
4	A	В	В						
5	A	В	В	В					
6	A	В	В	В	В				
7	A	В	В	В	В	В			
8	A	В	В	В	В	В	В		
9	A	В	В	В	В	В	В	В	

Solution (b) for Condition 2 when m = 5



The two treatments are not equally replicated.

(c) $V_T \cap W_1$ and $V_T \cap W_2$ are both non-zero, and $V_T = W_0 \oplus (V_T \cap W_1) \oplus (V_T \cap W_2)$.

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 - Partition the set of individuals into n sorts $S_1, ..., S_n$ of size $s_1, ..., s_n$, where $n \ge 2$.

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Theorem about this solution

Theorem

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For i = 1, ..., n, let \mathbf{w}_i be the vector whose entries are
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0 on all pairs which do not involve an individual of sort i
 1 on all pairs which involve a single individual of sort i
 2 on all pairs which involve two individuals of sort i

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- ► The vectors $\mathbf{w}_1, ..., \mathbf{w}_n$ span an n-dimensional subspace of $V_T \cap (W_0 \oplus W_1)$.
- ▶ If $\mathbf{v} \in V_T$ is orthogonal to \mathbf{w}_i for i = 1, ..., n then $\mathbf{v} \in W_2$.

Here m = 9, n = 2, $s_1 = 3$, $s_2 = 6$ and t = 9.

	1	2	3	4	5	6	7	8
2	A							
3	A	Α						
4	В	С	D					
5	В	С	D	Е				
6	D	В	С	F	I			
7	D	В	С	G	Н	Е		
8	С	D	В	Н	F	G	Ι	
9	С	D	В	I	G	Н	F	Ε

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3	Α	Α						
4	В	С	D					
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7	D	В	С	G	Н	Ε		
8	С	D	В	Н	F	G	Ι	
9	С	D	В	Ι	G	Н	F	Е

$$S_1 = \{1, 2, 3\}, T_1 = \{A\} \text{ and } t_1 = 1.$$

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	1	2	3	4	5	6	7	8
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3	A	Α						
4	В	С	D					
5	В	С	D	Е				
6	D	В	С	F	I			
7	D	В	С	G	Н	Е		
8	С	D	В	Н	F	G	Ι	
9	С	D	В	I	G	H	F	E

$$S_1 = \{1, 2, 3\}, T_1 = \{A\} \text{ and } t_1 = 1.$$

 $S_2 = \{4, 5, 6, 7, 8, 9\}, T_2 = \{E, F, G, H, I\} \text{ and } t_2 = 5.$

Here m = 9, n = 2, $s_1 = 3$, $s_2 = 6$ and t = 9.

	1	2	3	4	5	6	7	8
2	A							
3	A	Α						
4	В	С	D					
5	В	С	D	Е				
6	D	В	C	F	I			
7	D	В	С	G	Н	Е		
8	С	D	В	Н	F	G	Ι	
9	C	D	В	I	G	Н	F	Ε

$$S_1 = \{1, 2, 3\}, T_1 = \{A\} \text{ and } t_1 = 1.$$

 $S_2 = \{4, 5, 6, 7, 8, 9\}, T_2 = \{E, F, G, H, I\} \text{ and } t_2 = 5.$

 $\mathcal{T}_{12} = \{B, C, D\}$ and $t_{12} = 3$.

	1	2	3	4	5	6	7	8
2	A							
3	Α	В						
4	A	С	D					
5	Α	D	С	В				
6	Е	F	G	Н	I			
7	Е	G	Н	I	F	J		
8	Е	Н	I	F	G	K	L	
9	Е	I	F	G	Н	L	K	J

	1	2	3	4	5	6	7	8
2	A							
3	Α	В						
4	Α	С	D					
5	Α	D	С	В				
6	Ε	F	G	Н	I			
7	Е	G	Н	I	F	J		
8	Е	Н	I	F	G	K	L	
9	E	I	F	G	Н	L	K	J

$$S_1 = \{1\}$$
, $T_1 = \emptyset$ and $t_1 = 0$.

	1	2	3	4	5	6	7	8
2	A							
3	A	В						
4	A	C	D					
5	A	D	С	В				
6	Ε	F	G	Н	I			
7	Е	G	Н	I	F	J		
8	Е	Н	I	F	G	K	L	
9	Е	Ι	F	G	Н	L	K	J

$$S_1 = \{1\}, T_1 = \emptyset \text{ and } t_1 = 0.$$

$$S_2 = \{2, 3, 4, 5\}, T_2 = \{B, C, D\} \text{ and } t_2 = 3.$$

	1	2	3	4	5	6	7	8
2	A							
3	A	В						
4	A	С	D					
5	A	D	С	В				
6	Е	F	G	Н	I			
7	Е	G	Н	I	F	J		
8	Е	Н	I	F	G	K	L	
9	Е	I	F	G	Н	L	K	J

$$S_1 = \{1\}, T_1 = \emptyset \text{ and } t_1 = 0.$$

 $S_2 = \{2, 3, 4, 5\}, T_2 = \{B, C, D\}$

$$S_2 = \{2, 3, 4, 5\}, T_2 = \{B, C, D\} \text{ and } t_2 = 3.$$

$$S_3 = \{6, 7, 8, 9\}, T_3 = \{J, K, L\} \text{ and } t_3 = 3.$$

	1	2	3	4	5	6	7	8
2	A							
3	A	В						
4	A	С	D		_			
5	A	D	С	В				
6	Е	F	G	Н	I			
7	Е	G	Н	I	F	J		
8	Е	Н	I	F	G	K	L	
9	E	I	F	G	Н	L	K	J

$$S_1 = \{1\}, T_1 = \emptyset \text{ and } t_1 = 0.$$

 $S_2 = \{2, 3, 4, 5\}, T_2 = \{B, C, D\} \text{ and } t_2 = 3.$

$$S_3 = \{6,7,8,9\}, T_3 = \{J,K,L\} \text{ and } t_3 = 3.$$

$$\mathcal{T}_{12} = \{A\} \text{ and } t_{12} = 1.$$

Here m = 9, n = 3, $s_1 = 1$, $s_2 = 4$, $s_3 = 4$ and t = 12.

	1	2	3	4	5	6	7	8
2	A							
3	Α	В						
4	A	С	D					
5	A	D	С	В				
6	E	F	G	Н	I			
7	E	G	Н	I	F	J		
8	Е	Н	I	F	G	K	L	
9	E	I	F	G	Н	L	K	J

$$S_1 = \{1\}, T_1 = \emptyset \text{ and } t_1 = 0.$$

 $S_2 = \{2, 3, 4, 5\}, T_2 = \{B, C, D\} \text{ and } t_2 = 3.$ $S_3 = \{6,7,8,9\}, T_3 = \{I,K,L\} \text{ and } t_3 = 3.$

$$\mathcal{T}_{12} = \{A\} \text{ and } t_{12} = 1.$$
 $\mathcal{T}_{13} = \{E\} \text{ and } t_{13} = 1.$

Here m = 9, n = 3, $s_1 = 1$, $s_2 = 4$, $s_3 = 4$ and t = 12.

	1	2	3	4	5	6	7	8
2	A							
3	A	В						
4	A	С	D					
5	A	D	С	В				
6	Ε	F	G	Н	I			
7	Е	G	Н	I	F	J		
8	Е	Н	I	F	G	K	L	
9	E	I	F	G	Н	L	K	J

$$S_1 = \{1\}, T_1 = \emptyset \text{ and } t_1 = 0.$$

 $S_2 = \{2, 3, 4, 5\}, T_2 = \{B, C, D\} \text{ and } t_2 = 3.$

 $S_3 = \{6,7,8,9\}, T_3 = \{I,K,L\} \text{ and } t_3 = 3.$

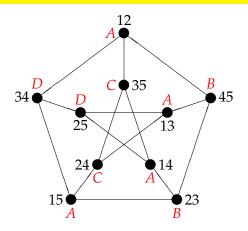
 $\mathcal{T}_{12} = \{A\} \text{ and } t_{12} = 1.$ $\mathcal{T}_{13} = \{E\} \text{ and } t_{13} = 1.$

 $\mathcal{T}_{23} = \{F, G, H, I\}$ and $t_{23} = 4$.

Design and Analysis of Networked Experiments

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Solution (c) for Condition 2 when m = 5



Treatment *A* occurs on all pairs involving individual 1. Each other treatment is involved with each other individual exactly once.

Terminology

For a wide range of structures on the set Ω , some statisticians call Condition 2 equivalent estimation.

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Some combinatorialists say that Condition 2 is satisfied if the treatments give an equitable partition of the graph.

References

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